

## Integration by Fourier Transform—INFR

The program INFR (**I**ntegration by **F**ourier Transform) is a subroutine subprogram that calculates the discrete value of an integral  $\int_0^{t=m\Delta t} x(t)dt$  ( $m = 0, 1, 2, \dots, N - 1$ ) by using the Fourier transform and the inverse Fourier transform when the equally spaced time history  $x(t)$  is given as  $N$  discrete-valued data  $x_m$  ( $m = 0, 1, 2, \dots, N - 1$ ).

### INFR ( Integration by Fourier Transform )

#### 【Purpose】

To integrate equally spaced time history data using the Fast Fourier Transform.

#### 【Usage】

( 1 ) How to connect

CALL INFR ( N, X, ND, DT)

Argument	Type	Parameter in calling program	Return Parameter
N	I	Total number of 1-D array X	Unchanged
X	R 1-D array ( ND )	Time history data to be integrated	Integrated time history data
ND	I	Dimension size of X in calling program (ND .GE. N)	Unchanged
DT	R	Time increment (unit: sec)	Unchanged

( 2 ) Necessary subroutines and function subprograms

FAST

( 3 ) Remarks

$N$  must be less than or equal to 8192. (But it can be changed easily.)

#### 【Calculation Method】

When  $N$  discrete-valued data  $x_m$  ( $m=0, 1, 2, \dots, N-1$ ) at equal interval  $\Delta t$  are given in the time domain,

first Fourier transform them to obtain the complex Fourier coefficients  $C_k$  in the frequency domain.

$$\left. \begin{aligned} S_0 &= 2 \left[ \frac{(N-1)C_0}{2} \left( \frac{\pi}{N} \right) - \sum_{k=1}^{N/2-1} \frac{J(C_k)}{k} \right] \\ S_k &= \left[ -1 + i \cot \left( \frac{\pi}{N} \right) k \right] C_0 \left( \frac{\pi}{N} \right) - \frac{i C_k}{k}, \quad S_{N-k} = S_k^* \quad k = 1, 2, \dots, N/2-1 \\ S_{N/2} &= - \left( \frac{\pi}{N} \right) C_0 \end{aligned} \right\}$$

Then, after performing the following operations, the discrete value of the integral can be obtained by performing the inverse Fourier transform.

$$\left( \int_0^t x dt \right)_m = \frac{N\Delta t}{2\pi} \sum_{k=0}^{N-1} S_k e^{i(2\pi km/N)} \quad m = 0, 1, 2, \dots, N-1$$

$$\left( \int_0^t x dt \right)_m = \int_0^{t=m\Delta t} x(t) dt \quad m = 0, 1, 2, \dots, N-1$$

The fast Fourier transform program FAST is used for the Fourier transform and the inverse Fourier transform. To make it convenient to use the Fourier, add a trailing zero to make the number of data a power of 2, and then complex the data by the 'INITIALIZATION' block in the program. At the end of the Fourier transform, the complex Fourier coefficients  $C_k$  are all multiplied by  $N$ , but the correction is done after the inverse Fourier transform is completed.

#### 【Program List】

C	*****	INFR	1
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C	CALL INFR(N, X, ND, DT)	INFR	12
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C	DESCRIPTION OF ARGUMENTS	INFR	14
C	N - TOTAL NUMBER OF DATA N.LE. 8192	INFR	15
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C	DT - TIME INCREMENT IN DATA	INFR	18
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C	SUBROUTINES AND FUNCTION SUBPROGRAMS REQUIRED	INFR	20
C	FAST	INFR	21
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C	SUBROUTINE INFR(N, X, ND, DT)	INFR	23
C		INFR	24
C	COMPLEX C(8192)	INFR	25

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        DIMENSION X (ND)                                INFR 26
        PARAMETER (P2=6.283185)                          INFR 27
C
C   INITIALIZATION                                      INFR 28
C
        DO 110 M=1, N                                    INFR 31
        C(M)=CMPLX(X(M), 0.)                             INFR 32
110 CONTINUE                                            INFR 33
        NT=2                                              INFR 34
120 IF (NT.GE.N) GO TO 130                              INFR 35
        NT=NT*2                                          INFR 36
        GO TO 120                                        INFR 37
130 IF (NT.EQ.N) GO TO 150                              INFR 38
        DO 140 M=N+1, NT                                INFR 39
        C(M)=(0., 0.)                                   INFR 40
140 CONTINUE                                            INFR 41
150 NFOLD=NT/2+1                                        INFR 42
        PN=P2/2./REAL(NT)                               INFR 43
C
C   FOURIER TRANSFORM                                  INFR 44
C
        CALL FAST (NT, C, 8192, -1)                     INFR 47
C
C   INTEGRATION                                        INFR 48
C
        C1=REAL(C(1))                                   INFR 51
        S1=REAL(NT-1)/2.*C1*PN                          INFR 52
        DO 160 K=2, NFOLD-1                              INFR 53
        S1=S1-AIMAG(C(K))/REAL(K-1)                     INFR 54
        C(K)=CMPLX(-1., 1./TAN(REAL(K-1)*PN))*C1*PN-    INFR 55
        (0., 1.)*C(K)/REAL(K-1)
        C(NT-K+2)=CONJG(C(K))                           INFR 56
160 CONTINUE                                            INFR 57
        C(1)=CMPLX(S1*2., 0.)                           INFR 58
        C(NFOLD)=CMPLX(-C1*PN, 0.)                     INFR 59
C
C   FOURIER INVERSE TRANSFORM                          INFR 60
C
        CALL FAST (NT, C, 8192, +1)                     INFR 63
        DO 170 M=1, N                                    INFR 64
        X(M)=REAL(C(M))/P2*DT                            INFR 65
170 CONTINUE                                            INFR 66
        RETURN                                           INFR 67
        END                                              INFR 68

```

**【Example】**

Read the acceleration time history from the file EQ.01, integrate it with the subroutine **INFR** to obtain the velocity time history, and then differentiate it with the subroutine **DIFR** to return to the original acceleration time history.

```

C
        DIMENSION DATA(800), VEL(800), ACC(800), DYY(800)
C

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```

READ(5, 501) DT, NN, (DATA(M), M=1, NN)
CALL INFR (NN, DATA, 800, DT)
DO 110 M=1, NN
  VEL(M)=DATA(M)
110 CONTINUE
  CALL DIFR (NN, DATA, 800, DT)
  DO 120 M=1, NN
    ACC(M)=DATA(M)
120 CONTINUE
  STOP
C
501 FORMAT (T51, F10.0, I10/(8F10.0))
END

```

Output: The integrated data is stored in array *VEL*, and the differentiated data is stored in array *ACC*. These are shown in the following figures in the order of the original acceleration time history, the integrated velocity time history, and the differentiated acceleration time history.

